

# MR3000C Vibration / Motion Measurement System

The MR3000C in SYSCOM's rugged RED BOX is a compact vibration/motion measurement system. As such it meets all user experctation in a state-of-the-art device and thus is a highly reliable and efficient tool for many applications in

#### **Civil Engineering**

- Industrial Vibrations
- Construction Site Monitoring
- □ Tunneling
- Truck and Rail Traffic
- Blasting Monitoring
- Model Verification

#### Earthquake Engineering

- Building Monitoring
- □ Monitoring of Structures (Dams, Bridges..)

#### Geology

□ Soil Characterization

#### Earth Science

- □ Earthquake Monitoring (seismic Intensity)
- Continuous data stream in MiniSeed/SeedLink format

#### Major features are

- □ Compact unit containing sensor, digital recorder and communications
- □ ARM/DSP Technology
- □ Removable SD Card Memory
- Embedded Web Server for easy configuration and control
- □ Precise timing (GPS or IEEE-1588 PTP)
- □ Power over Ethernet (PoE)
- □ Wide dynamic range
- □ Wireless connectivity

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# **Technical Specifications MR3000C**

# **Data Acquisition**

Principle	4 <sup>th</sup> order delta-sigma ADC per channel
Resolution	24 bit
Sampling-rate	50, 100, 200, 400, 500, 800, 1'000 sps, others on request
Number of channels	3
Channel to channel skew	None – simultaneous sampling on all channels
Dynamic range	Typ. 130dB@250, 127dB@500 sps
Data Filter	FIR & IIR digital filters
Trigger Filter	Digital IIR filter: 0.5 - 15 Hz band-pass (Strong Motion Applications)
	Others on request

#### Trigger and De-trigger

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Principle	Level trigger or STA/LTA or combined
Trigger voting logic	Predefined AND or OR combinations, individual channel votes
Level trigger	0.003 to 100% full scale
STA / LTA (Strong Motion)	STA: 0,1 to 25s, LTA: to 250s, Ratio: 0,1 to 25, LTA latched/unlatched
Smart Trigger / De-Trigger	Automatic adjustment of trigger level

# Microprocessor

#### Recording

necorulity		
Principle	Event recording (time history), continuous time recording or manually triggered	
Header	Contains status information at time of trigger and event summary	
Pre-event recording	1 - 30 seconds (in 1 sec steps)	
Post-event recording	1 - 100 seconds (in 1 sec steps)	
Max. recording time	Event recording: unlimited	
Non volatile Memory	Internal and flash and removable SD card	
Alarm triggers		
Principle	Multiple level triggers with various notification options (individually settable for each axis)	
Range	0.1 % to 100% full scale	
Precision timing		
System Clock	1 ppm, this clock is disciplined by GPS, NTP or IEEE 1588 to < 0.1 ppm	
Data / user interface		
Intelligent Alerting	System initiates communications or sends text message (SMS) or e-mail when an event is detected	
Web Interface	Easy to use command & control through embedded web server	
FTP	Built-in FTP client to push data to an FTP-server	
Display		
3 LED	Run, Recording, Warning/Error	
LCD-Display	Status information, important settings.	
Wireless Communication		
WiFi	IEEE 802.11b/g/n compliant	
Mobile Network (option)	Multi-Band UMTS / HSDPA / WCDMA / GSM / GPRS / EDGE	

### **Power Supply**

Supply Voltage	9 - 13.5VDC or 48V PoE
Power Consumption	2 W (velocitymeter)
(W/O wireless communication)	3 W (accelerometer)

### I/O and Connectors

Туре	Metallic self-latching push-pull connectors with positioning key (LEMO)
Power	Metallic connector with protective GND
GPS	Connector for external GPS
LAN / PoE	Communication with PC or network - Ethernet 100BaseT

# Sensors (Internal)

#### Triaxial Velocitymeter (MS3003+)

Туре	Velocity sensor with linearized frequency response
	A3HV 315/1 (triaxial) (according to DIN 45669)
Principle	Geophone
Measuring range full scale	± 100 mm/s
Frequency range	1 - 350 Hz (linear ±10% frequency response)
Case-to-coil motion	4 mm p-p
Dynamic range	> 130 dB
Linearity / Phase	According to DIN 45669 (class 1)
Cross axis sensitivity	According to DIN 45669 (<5%)

#### **Triaxial Accelerometer**

	MS3004+	MS3006+
Principle	The sensing element is an analog force feedback accelerometer featuring a variable capacitance, silicon bulk-micro machined acceleration sensor (MEMS) and a custom low-power mixed-signal integrated circuit (ASIC). The MEMS/ASIC custom design forms a DC coupled analog servo accelerometer. Micro mechanical (MEMS), force balance accelerometer (FBA)	
Hysteresis	No	ne
Dynamic range (100 Hz BW)	typ. 120 dB (±2g)	typ. 110 dB (±4g)
Noise (10 to 1000 Hz)	typ. 300 ng <sub>ms</sub> ∕√Hz	typ. 900 ng <sub>ms</sub> ∕√Hz
Noise (0.1 to 100 Hz)	typ. 3.3 μg <sub>ms</sub>	typ. 11 μg <sub>rms</sub>
Natural frequency	Frequency response DC to >1000 Hz	
Measuring range	±2 g standard, ±1 g	$\pm$ 4 g standard, $\pm$ 2g
Non-Linearity	< 1 % of full scale	< 1.5 % of full scale
Scale factor temp. drift (±2g)	typ. <150ppm/°C	typ. <200ppm/°C
Zero point offset drift (±2g)	typ. <300µg/°C	typ. <400µg/°С
Orientation	Triaxial, horizontal (floor) mounting or vertical (wall mounting)	
Self-test	Test-pulse	
Cross axis rejection	>40	dB

### **Dimensions**

Housing	Aluminum, 120 x 180 x 100 mm
Weight	1.5 kg
Protection degree	IP 65 (splash-proof)

### Regulations

Electrical Safety	In compliance with EN 50 081 and EN 50 082
EMI/RFI	In compliance with EN 61010
Environmental	Shock: 30 g/11 ms half-sine
	Heat: -20° up to +70°C
	Humidity: up to 100% rh
	Vibration: up to 5 g (operating)
Conformity	(€

### **Ordering Information**

Vibration/Motion Measurement System	MR3000C with internal MS3003+ Velocitymeter MR3000C with internal MS3004+ Accelerometer 1g or 2g MR3000C with internal MS3006+ Accelerometer 2g or 4g
Power supply	External battery package with integrated AC/DC converter/charger
	External AC/DC converter
Mounting Platform	Mounting platform for MR3000C with leveling bubble
GPS timing	GPS receiver and antenna
Carrying case	For MR3000C and battery package

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